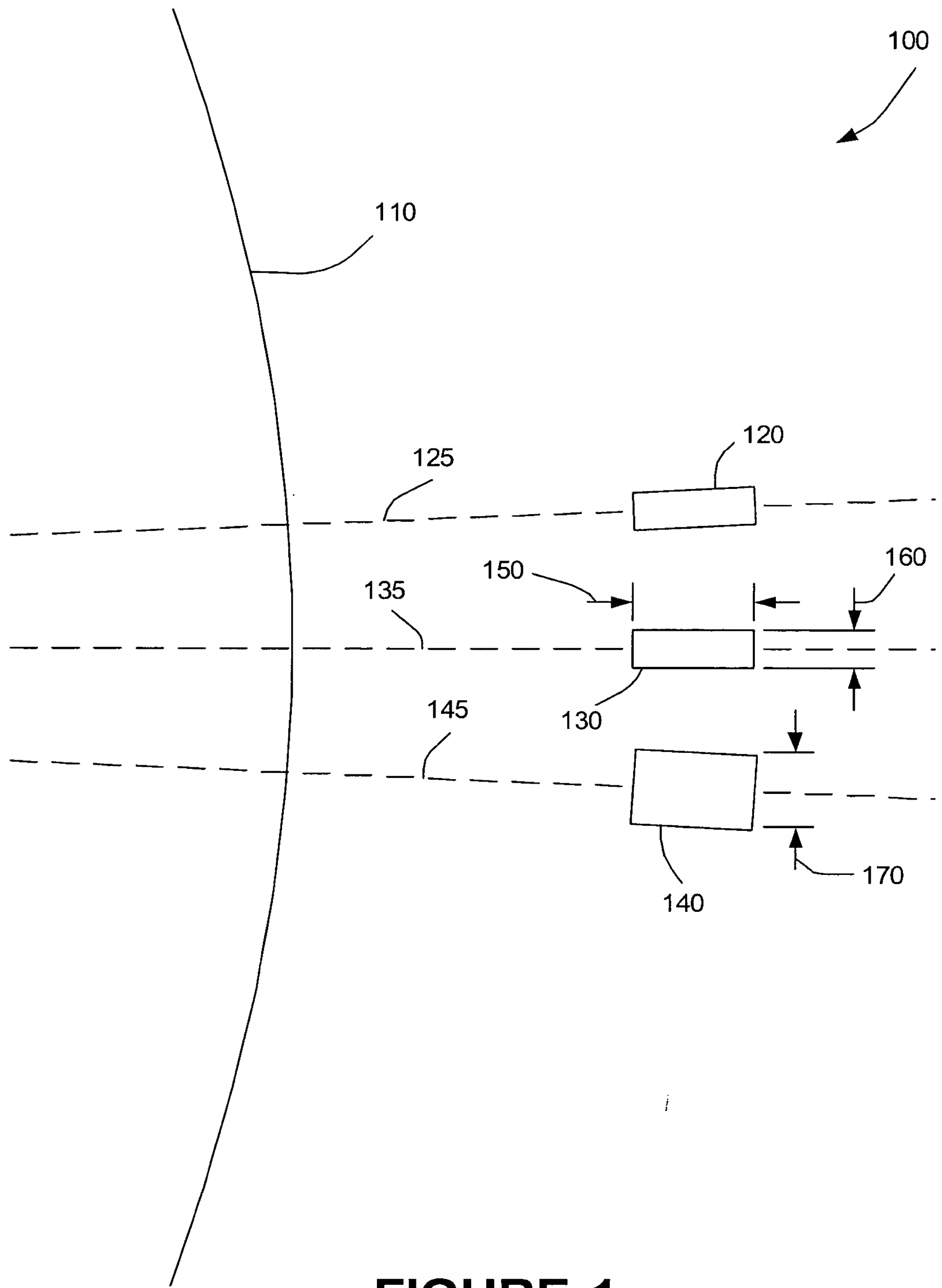
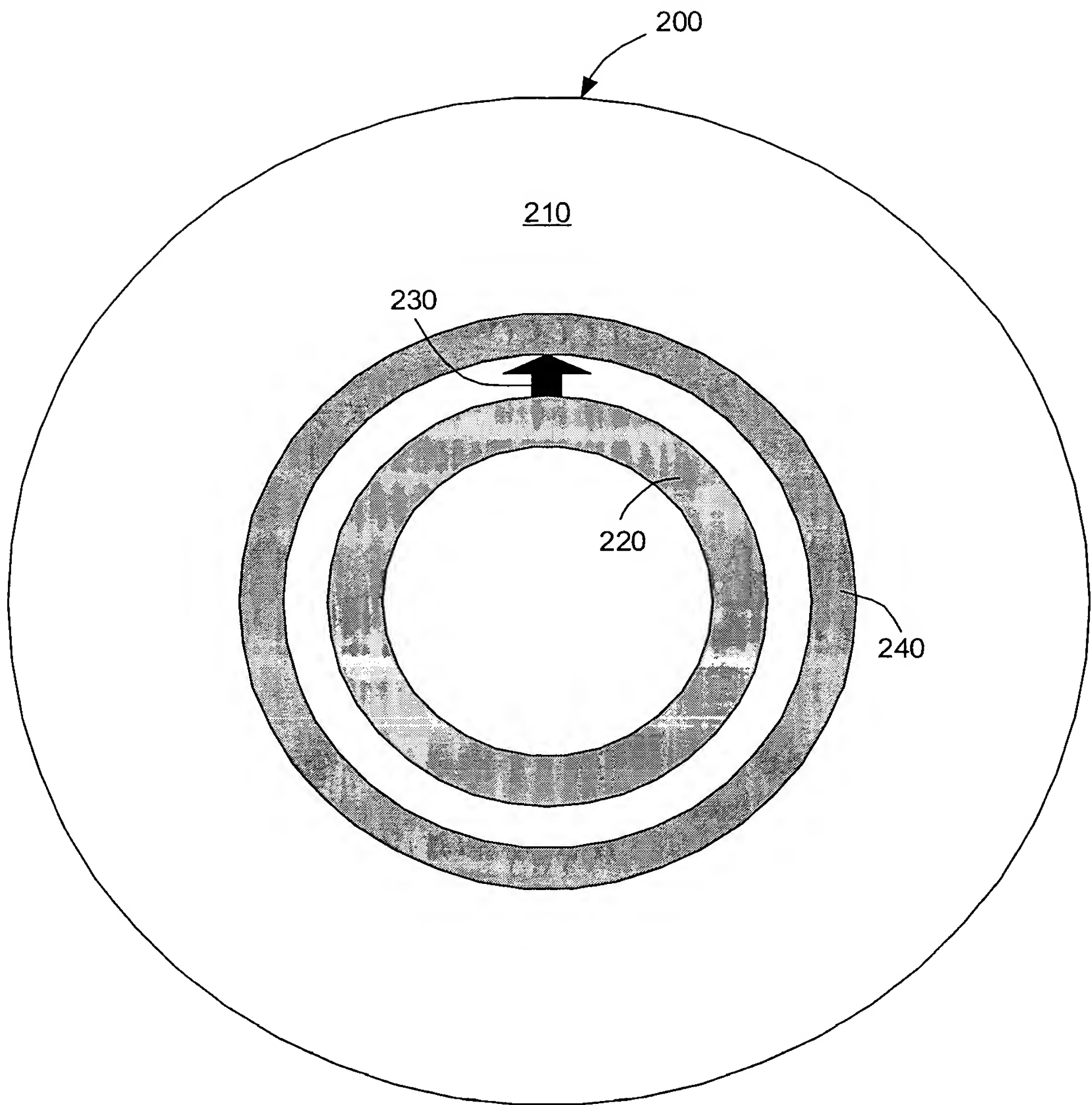


FIG. 1 is a schematic diagram of a system 100 for monitoring a curved surface 110. The system 100 includes a sensor array 120, a processing unit 130, and a display unit 140. The sensor array 120 is positioned to receive signals from the curved surface 110. The processing unit 130 is connected to the sensor array 120 and the display unit 140. The display unit 140 displays the signals received from the sensor array 120. The system 100 is used to monitor the curvature of the surface 110.

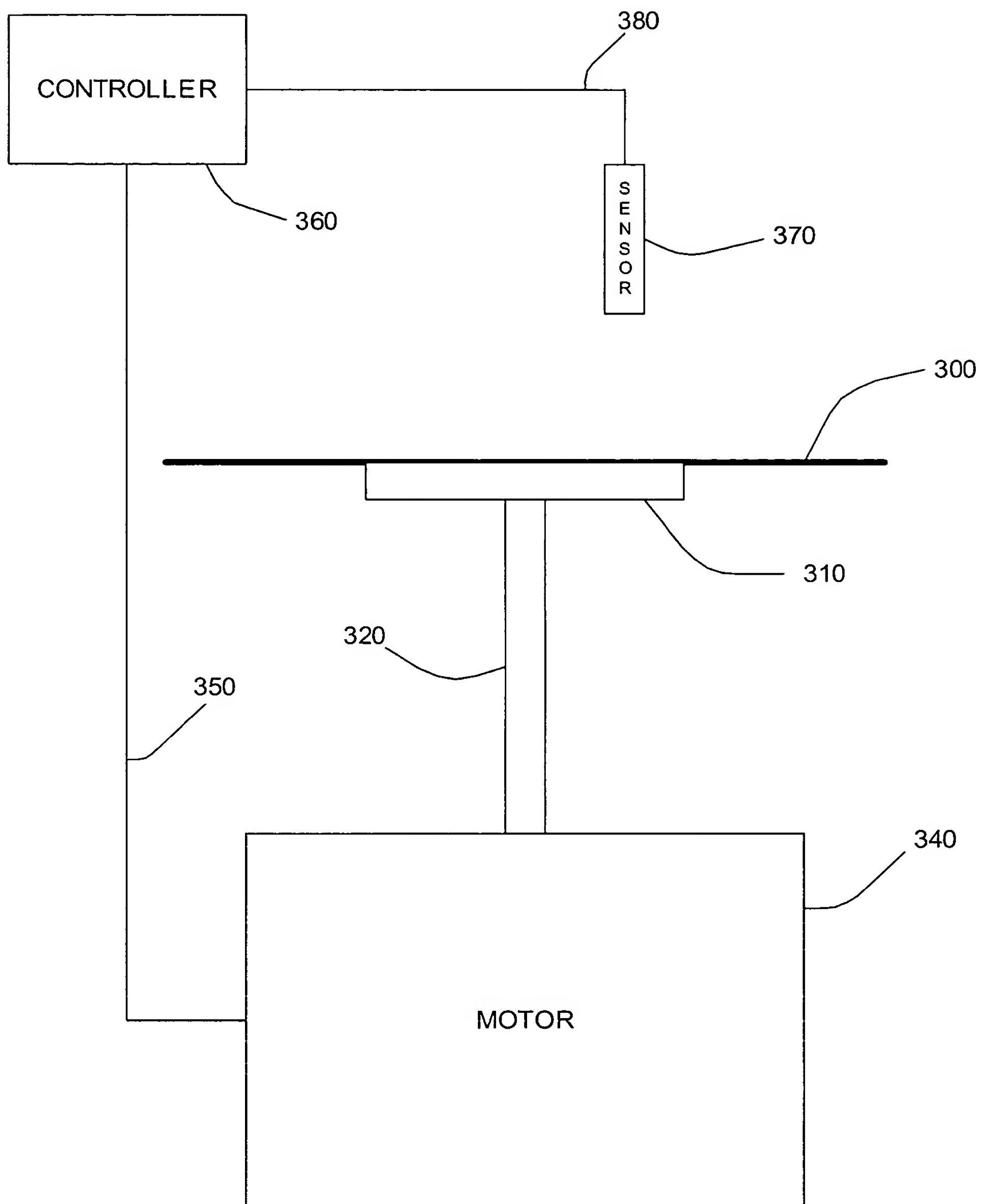


**FIGURE 1**



**FIGURE 2**

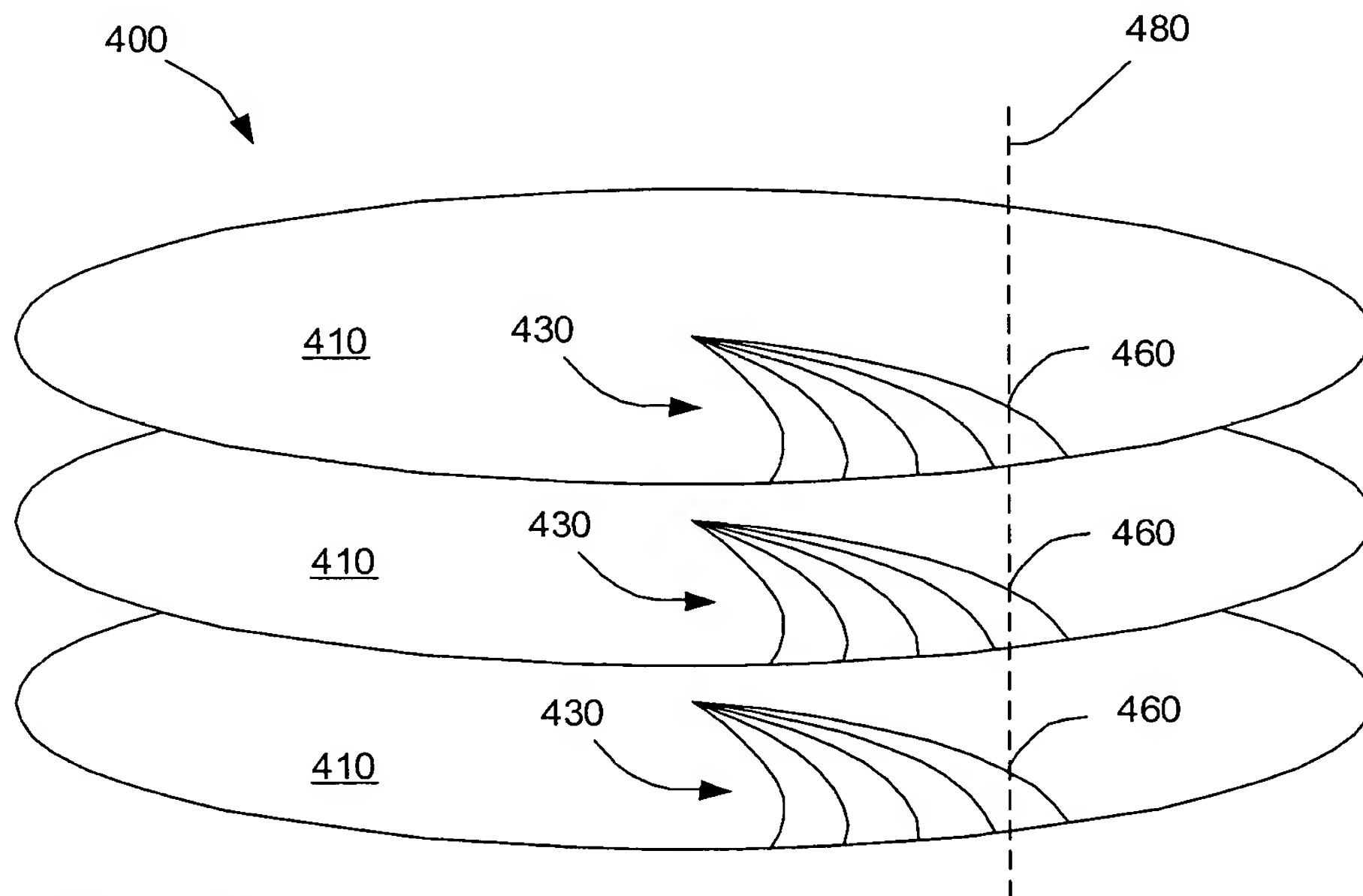
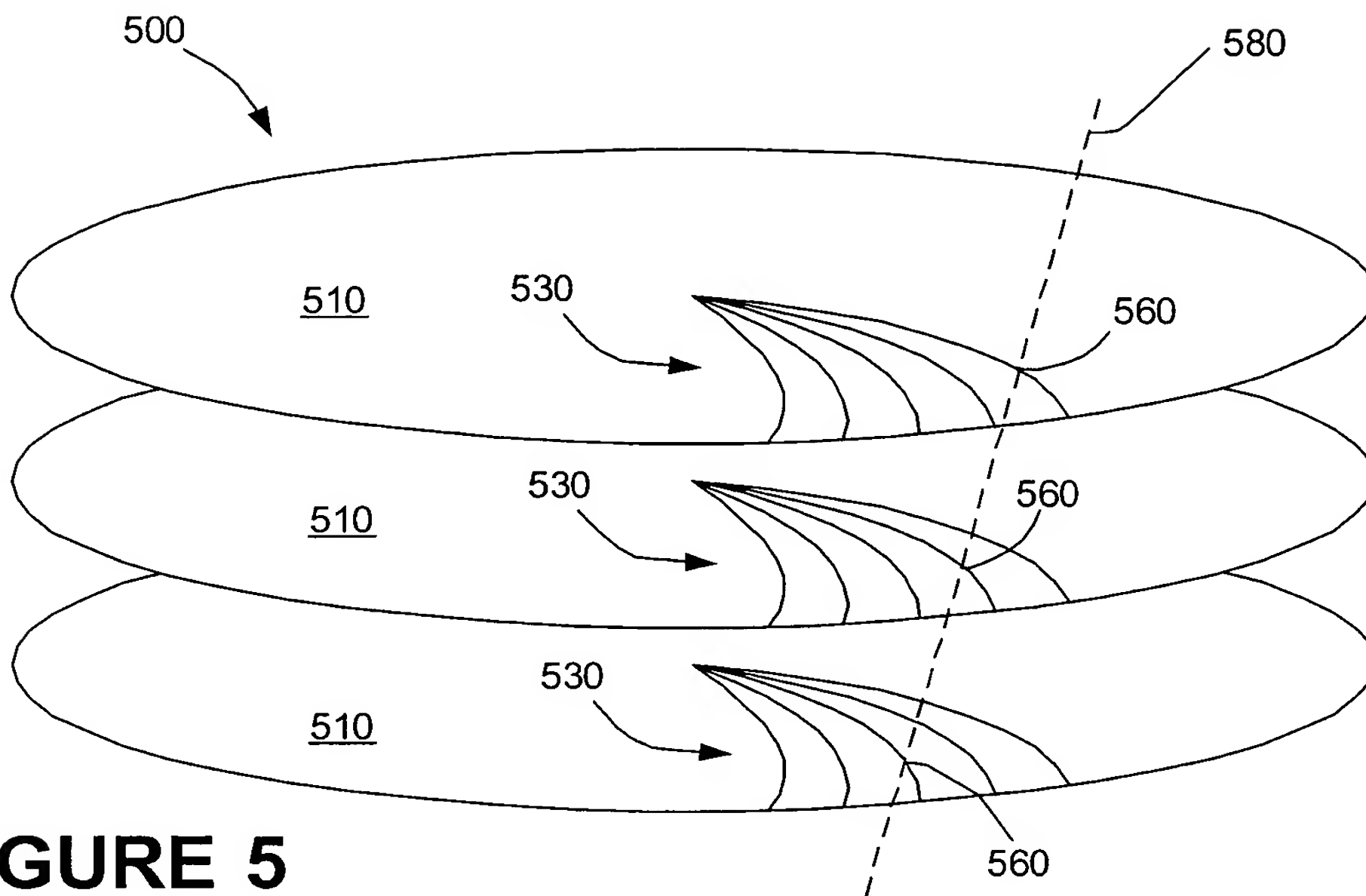
FIG. 3 is a schematic diagram of a system 300 for controlling a motor 340. The system 300 includes a controller 360, a sensor 370, a motor 340, and a shaft 320. The controller 360 is connected to the sensor 370 via a line 380. The controller 360 is also connected to the motor 340 via a line 350. The sensor 370 is connected to the shaft 320 via a line 310. The shaft 320 is connected to the motor 340 via a line 330.



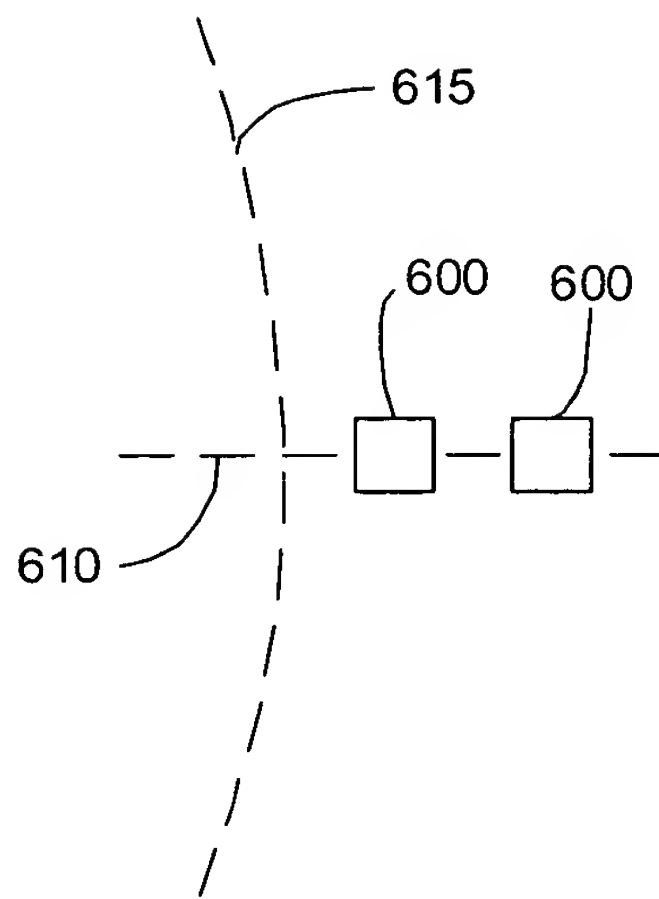
**FIGURE 3**

FIG. 5 is a schematic diagram of a multi-layered structure 500. The structure 500 is composed of three stacked layers, each labeled 510. Each layer 510 contains a series of curved lines 530 that converge towards a central point. A dashed line 580 passes through the structure, and a label 560 points to the curved lines 530.

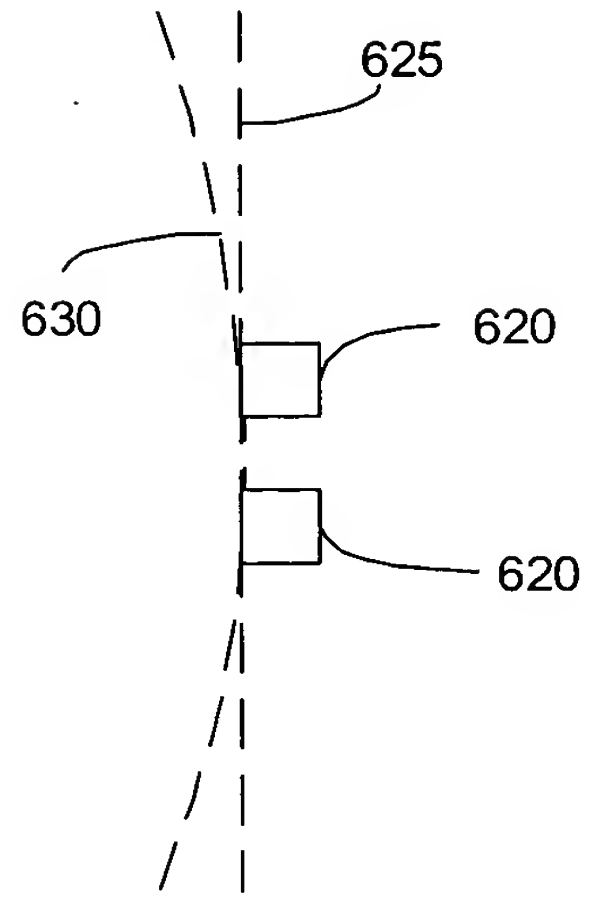
**FIGURE 5**



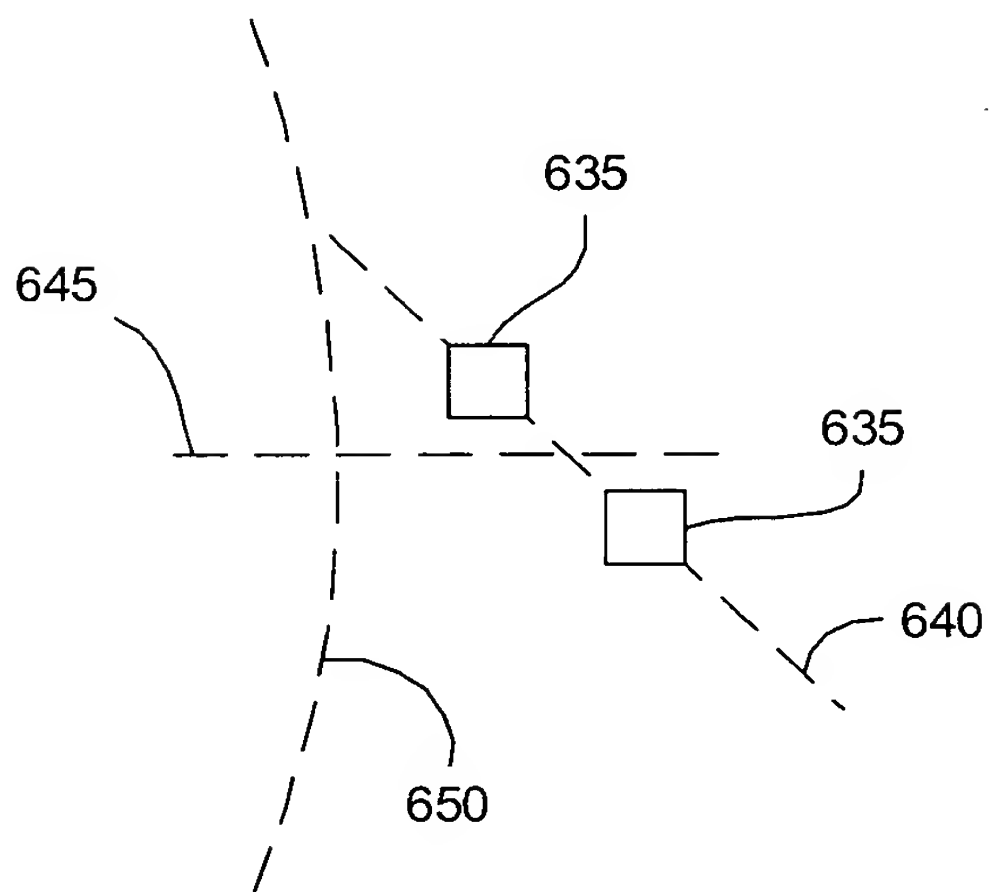
**FIGURE 4**



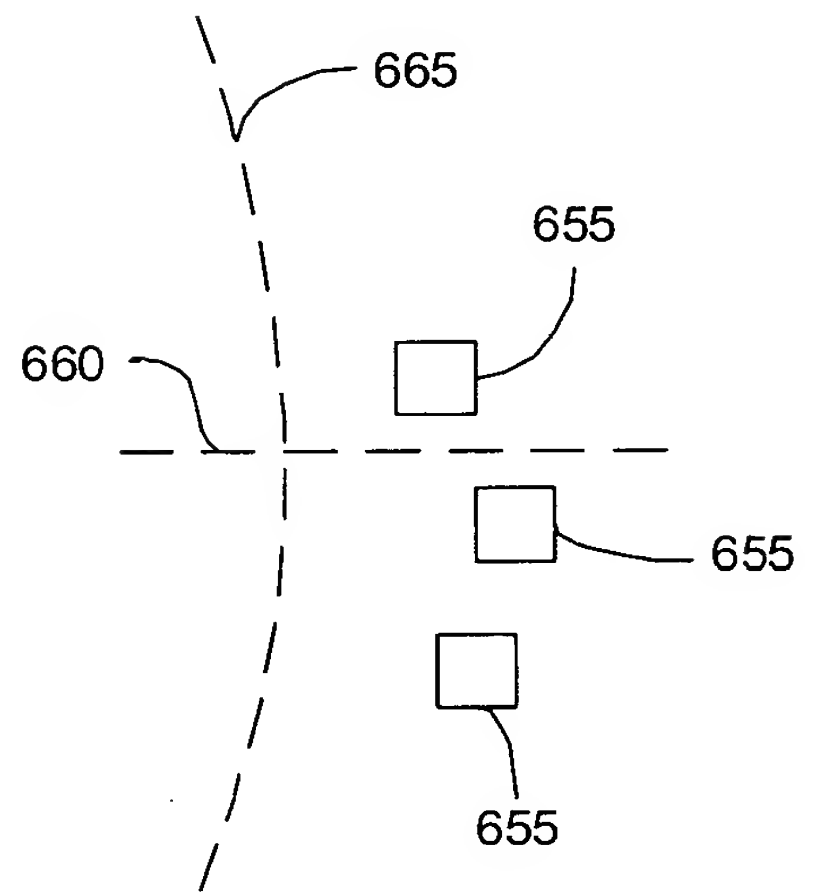
**FIGURE 6A**



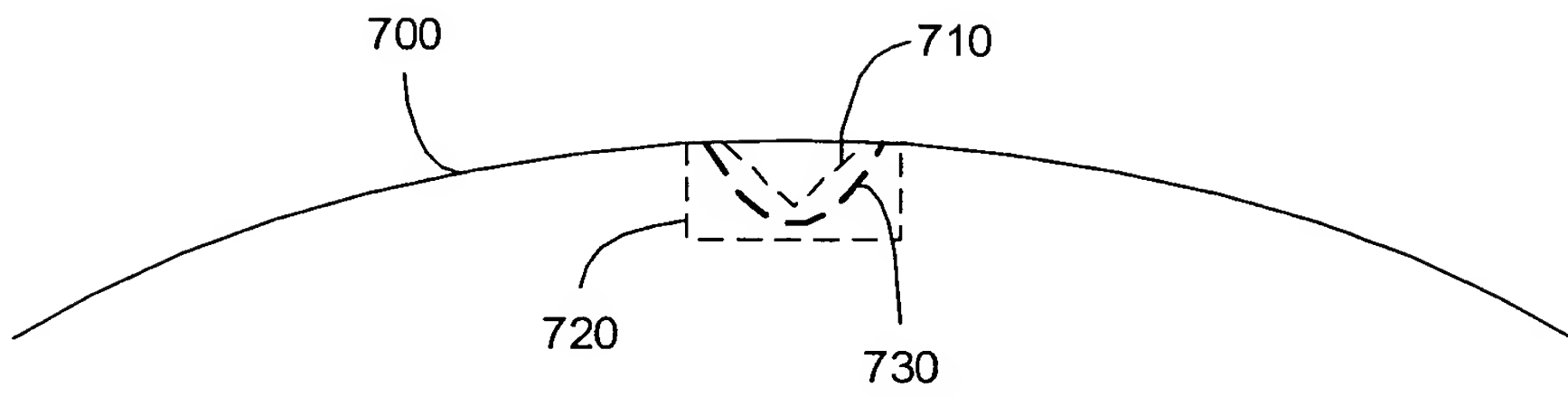
**FIGURE 6B**



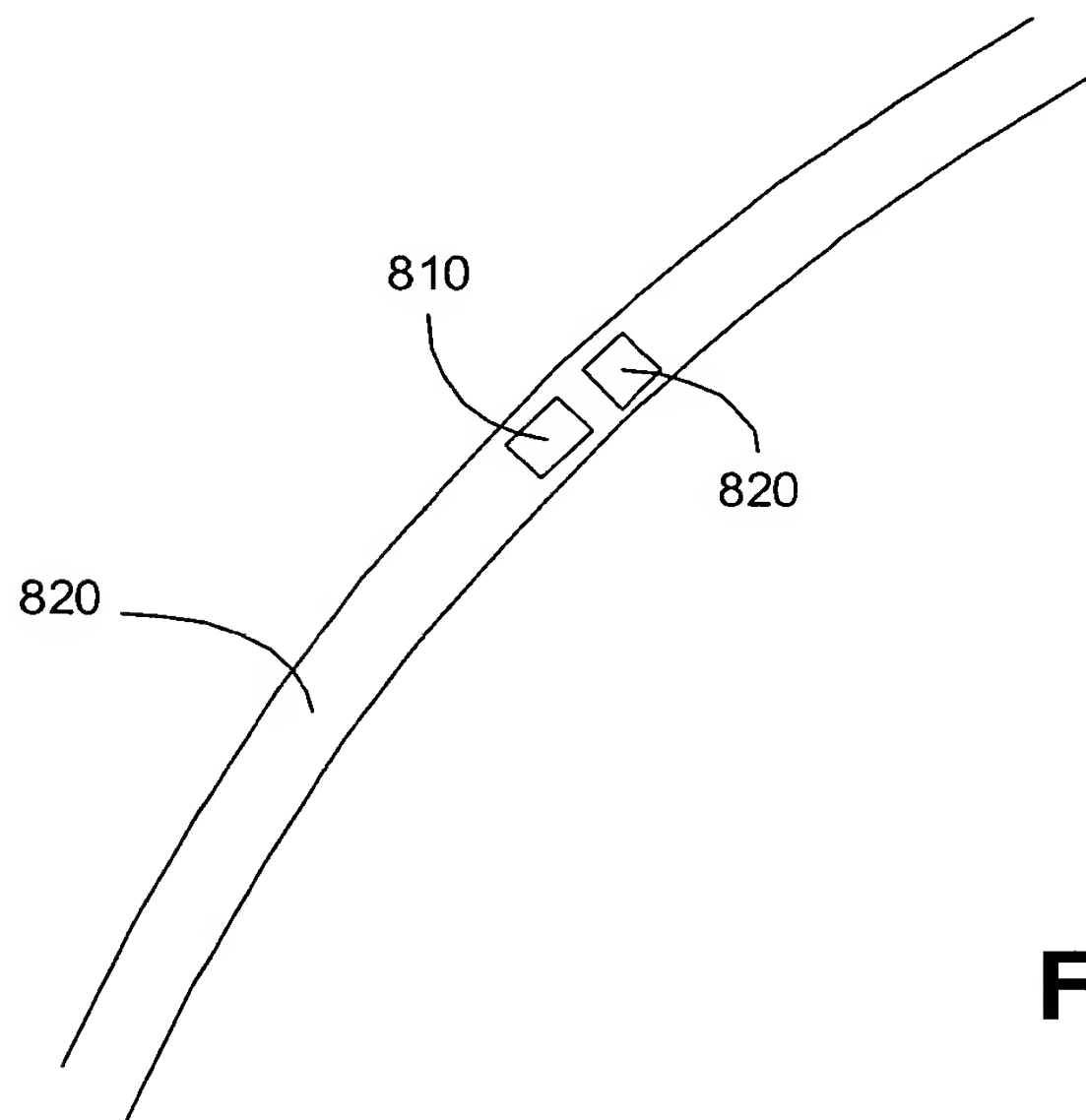
**FIGURE 6C**



**FIGURE 6D**



**FIGURE 7**



**FIGURE 8**